

# InMax ¼ turn actuators – size S

Electrical rotary actuators for use in safe areas

3-pos. / 0...10 VDC / 4...20 mA control mode, with feedback, 24...240 VAC/DC, 95° angle of rotation  
5/10 Nm, 15/30 Nm without and 5/10 Nm, 15 Nm with safety operation (spring return)

InMax - ... - Y  
InMax - ... - YF  
InMax - ... - VAS  
InMax - ... - CTS

Subject to change!

**Compact. Easy installation. Universal. Cost effective. Safe.**

Type	Torque	Supply	Motor running time	Spring return	Control mode	Feedback	Wiring diagram
InMax- 5.10 - Y	5 / 10 Nm	24...240 VAC/DC	7,5 / 15 / 30 / 60 / 120 s/90°	–	3-pos., 0...10 VDC, 4...20 mA	0...10 VDC, 4...20 mA	SB 5.0 – 5.3
InMax-15.30 - Y	15 / 30 Nm	24...240 VAC/DC	7,5 / 15 / 30 / 60 / 120 s/90°	–	3-pos., 0...10 VDC, 4...20 mA	0...10 VDC, 4...20 mA	SB 5.0 – 5.3
InMax- 5.10 - YF	5 / 10 Nm	24...240 VAC/DC	7,5 / 15 / 30 / 60 / 120 s/90°	3 or 10 s/90°	3-pos., 0...10 VDC, 4...20 mA	0...10 VDC, 4...20 mA	SB 5.0 – 5.3
InMax- 15 - YF	15 Nm	24...240 VAC/DC	7,5 / 15 / 30 / 60 / 120 s/90°	3 or 10 s/90°	3-pos., 0...10 VDC, 4...20 mA	0...10 VDC, 4...20 mA	SB 5.0 – 5.3
InMax- ... - VAS	Types as above with stainless steel housing for aggressive ambient (cable glands brass nickel-plated)						
InMax- ... - CTS	Types as above with aluminium housing and seawater resistant C5-M painting (cable glands brass nickel-plated)						

## Product views and applications

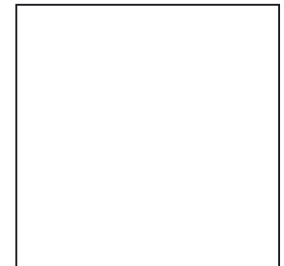
Safety damper



Ball valve



Throttle valve



## Description

The InMax actuators are a revolution for safety, control and shut-off dampers, VAV systems, ball valves, throttle valves and other motorized applications for HVAC systems in chemical, pharmaceutical, industrial and offshore/onshore plants.

IP66 protection, small dimensions, only 3,5 kg weight, universal functions and technical data, an integrated heater and an optional stainless steel housing guarantee safe operation even under difficult environmental conditions. High quality brushless motors guarantee long life.

All actuators are programmable and adjustable on site. Special tools or equipment are not required. Motor running times and torques as well as spring return times, according to the actuator type, are selectable or adjustable on site. The integrated universal power supply is self adaptable to input voltages in the range of 24...240 VAC/DC. Furthermore it is possible to perform control signal inverting and compulsion control by certain connections. The actuators are 100 % overload protected and self locking.

...Max-...-YF actuators are equipped with spring return fail safe function. Standard shaft connection is a double square direct coupling with 12 x 12 mm.

Different accessories are available to adapt auxiliary switches, terminal boxes or adaptions for ball valves and throttle valves and other armatures.

## Highlights

- Industrial use
- Universal supply unit from 24...240 VAC/DC
- 5 different motor running times 7,5–15–30–60–120 s/90°, adjustable on site
- 2 different spring return running times ~ 3–10 s/90°, selectable on site
- 3-pos. and 0...10 VDC, 4...20 mA control mode with or without spring return function
- Feedback signals 0...10 VDC and 4...20 mA
- Reverse function
- 5–10–15–30 Nm actuators in the same housing size
- 100 % overload protected and self locking
- Compact design and small dimension (L x W x H = 210 x 95 x 80 mm)
- Direct coupling to the damper shaft with double square connection 12 x 12 mm
- 95° angle of rotation inclusive 5° pretension
- Robust aluminium housing (optional stainless steel + seawater resistant C5-M painting)
- IP66 protection
- Simple manual override included + preparation for comfortable manual override
- Gear made of stainless steel and sinter metal
- Weight only ~ 3,5 kg
- Integral heater for ambient temperatures down to –40 °C
- Integral safety temperature sensor
- Integral equipment for manual adjustment (push button, lamp, switch)
- Preparation for adaptable and adjustable auxiliary switches type ...Switch
- Wide range of accessories

Technical data	InMax- 5.10 -Y	InMax- 15.30 -Y	InMax- 5.10 -YF	InMax- 15 -YF
Torque motor (min.)	5 / 10 Nm selectable on site	15 / 30 Nm selectable on site	5 / 10 Nm selectable on site	15 Nm
Torque spring (F)	without F	without F	min. 10 Nm	min. 15 Nm
Dimension of external torque	Above mentioned torques are min. torques in blocked position, external torque should be max. 80 % of max. actuator torque but min. 3 Nm			
Supply voltage / frequency	24...240 VAC/DC, ± 10 %, self adaptable, frequency 50...60 Hz ± 20 %			
Power consumption	max. starting currents see ❶Extra information (in acc. with voltage, I <sub>start</sub> >> I <sub>rated</sub> ), approx. 5 W holding power, approx. 16 W for heater			
Protection class	Class I (grounded)			
Angle of rotation and indication	95° incl. ~ 5° pretension, mechanical value indication			
Working direction	Selectable by left/right mounting to the damper/valve shaft			
Motor running times	7,5 / 15 / 30 / 60 / 120 s/90° selectable on site			
Motor	Brushless DC motor			
Spring return (F)	without F	without F	spring return in the event of loss of power	
Spring return running time (F)	without F	without F	spring return in ~ 3 or 10 s/90°, selectable on site	
3 sec. mode – spring return	without F	without F	in acc. with external torque ~ 3 to 4 s/90° angle of rotation	
Safety operations at 10 sec.	min. 10,000 in acc. with construction of damper and ambient			
at 3 sec.	min. 1,000 in acc. with construction of damper and ambient			
Response time spring return	up to 1 sec. after power failure			
Control mode Y	3-pos., 0...10 VDC, 4...20 mA in acc. with wiring, selectable on site. Galvanic separation between supply and Y-signal			
Feedback signal U	0...10 VDC, 4...20 mA in acc. with wiring, selectable on site, both signals are available at the same time			
Resistance of Y and U signals	<b>Input signal:</b> U <sub>Y</sub> 0...10 VDC at 10 kΩ, Y <sub>1</sub> 4...20 mA at 100 Ω. <b>Feedback signal:</b> U <sub>U</sub> 0...10 VDC at 1.000...∞ Ω, U <sub>1</sub> 4...20 mA at 0...800 Ω			
Reverse function	Bridge between wiring 3 and 4 (signal wise) gets a reverse function of Y and U			
Compulsion control	In modulation mode an On-off compulsion control can be performed by external connection/wiring independently from the modulating signal			
Adjustment of Y and U	In case of external mechanical limitation of the angle of rotation, it is possible to perform an adjustment drive started by touching the button			
Axle of the actuator	Double square 12 × 12 mm, direct coupling, 100 % overload protected and self locking up to 15 Nm			
Electrical connection	2 cable glands ~ 1 m each, diameter of wires 0.5 mm². Connections require a terminal box!			
Diameter of cable	~ Ø 7.1 + 7.4 mm	~ Ø 7.1 + 7.4 mm	~ Ø 7.4 mm each	~ Ø 7.4 mm each
Cable gland	M16 × 1.5 mm standard cable and wire entries			
Manual override	Use delivered socket wrench, max. 4 Nm			
Integral heater	Integral, controlled heater for ambient temperature down to -40 °C			
Housing material	Aluminium die cast housing, painted. Optional in stainless steel V4A / AISI 316 (...-VAS) or seawater resistant C5-M painting (...-CTS)			
Dimensions	L × W × H = 210 × 95 × 80 mm, for diagrams see ❶Extra information			
Weight	~ 3,5 kg aluminium housing, stainless steel ~ 7 kg			
Ambients	Storage temperature -40...+70 °C, working temperature -40...+50 °C			
Humidity	0...90 % rH, non condensing			
Operating 7,5 sec. motor run time	at 24 V 50 % ED S3 (ED = duty cycle)			
≥ 15 sec. motor run time	at 15 / 30 / 60 / 120 s 100 % of ED is permitted			
Accuracy electrically	~ 100 steps			
Self adjustment	Before initial operation you need to start the self adjustment mode for „gentle blockade“ and adjustment of rotation angle			
Maintenance	Maintenance free relative to function, maintenance must comply with regional standards, rules and regulations			
Wiring diagrams	SB 5.0 / 5.1 / 5.2 / 5.3			
Delivery	Actuator with 2 × 1 m cable, 4 screws M4 × 100 mm, 4 nuts M4, Allen key for simple manual override			
Parameter at delivery	5 Nm, 30 s/90°	15 Nm, 30 s/90°	5 Nm, 30 s/90°	15 Nm, 30 s/90°

## Approbations

EMC	2004/108/EC
Low voltage	2006/95/EC
IP-Protection	IP66 in acc. with EN 60529

## Special solutions and accessories

...-VAS	Types in stainless steel housing V4A / AISI 316 Cd / DIN EN 1.4581
...-CTS	Types in aluminium housing with C5-M finish, parts nickel-plated
InBox-Y/S...	Terminal boxes
MKK-S	Mounting bracket for boxes type ...Box-... directly on actuator
InSwitch	2 external aux. switches, adjustable
HV-S...	Comfortable manual override for...Max actuators size S
KB-S	Clamp for damper shafts $\varnothing 10...20$ mm and $\square 10...16$ mm
AR-12-xx	Reduction part for 12 mm square connection to 11, 10, 9 or 8 mm shafts
Kit-S8	Cable glands nickel-plated
Adaptions	for dampers and valves on request

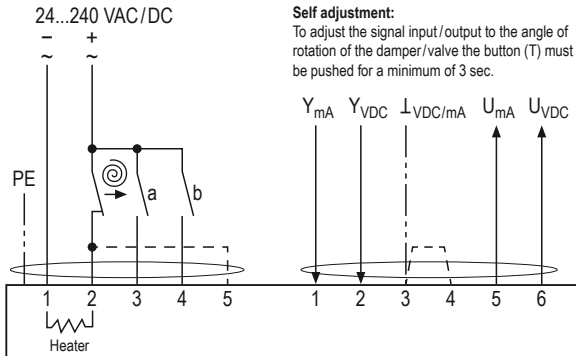
## Electrical connection

All actuators are equipped with a universal supply unit working at a voltage range from 24...240 VAC/DC. The supply unit is self adjusting to the connected voltage!  
 The safety operation of the spring return function works if the supply voltage is cut.

For electrical connection a terminal box is required (e.g. InBox).  
 An over-current protection fuse < 10 A has to be provided by installer.  
 Note: the initial current is appr. 2 A for 1 second.

### Modulating / 3-pos. – with / without spring return

SB 5.0



#### Selection of running time for spring return:

Spring return in ~ 10 s = Standard wiring  
 Spring return in ~ 3 s = Additional wiring on terminal 5

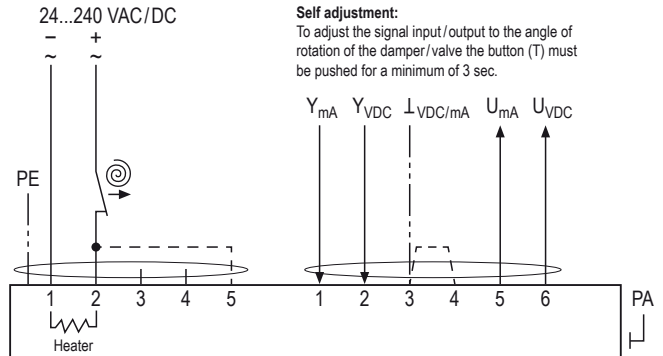
#### Reverse function:

Bridge 3–4 reverses the input and output signals

#### Function and enforcement control of switch a and b in modulating mode:

- a closed – **Forced-ON** (OFF) in acc. to left/right mounting of actuator
- b closed – **Forced-OFF** (ON) in acc. to left/right mounting of actuator

### Modulating – with / without spring return (no enforcement) SB 5.1



#### Selection of running time for spring return:

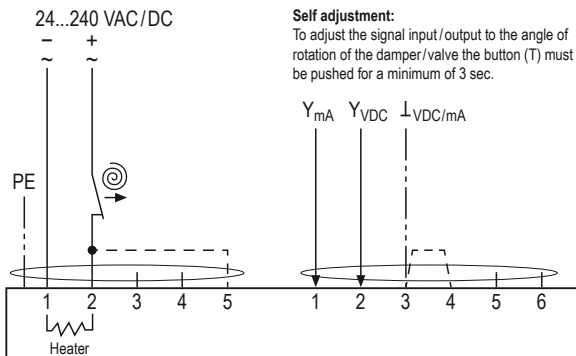
Spring return in ~ 10 s = Standard wiring  
 Spring return in ~ 3 s = Additional wiring on terminal 5

#### Reverse function:

Bridge 3–4 reverses the input and output signals

### Modulating – with / without spring return (no feedback) SB 5.2

SB 5.2



#### Selection of running time for spring return:

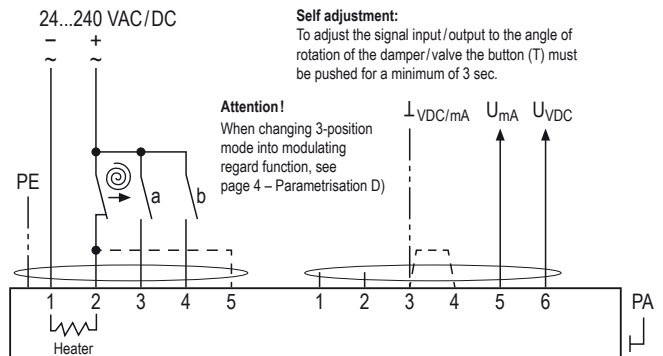
Spring return in ~ 10 s = Standard wiring  
 Spring return in ~ 3 s = Additional wiring on terminal 5

#### Reverse function:

Bridge 3–4 reverses the input signals

### 3-pos. – with / without spring return + feedback SB 5.3

SB 5.3



#### Selection of running time for spring return:

Spring return in ~ 10 s = Standard wiring  
 Spring return in ~ 3 s = Additional wiring on terminal 5

#### Reverse function:

Bridge 3–4 reverses the output signals

#### 3-pos. control mode:

- a closed, b open – **ON** (OFF) in acc. to left/right mounting of actuator
- b closed, a open – **OFF** (ON) in acc. to left/right mounting of actuator

## Installation



InBox

Y: 0...10 V / 4...20 mA  
 U: 0...10 V / 4...20 mA

supply \*  
 24...240 VAC/DC ± 10 %

\* electrical wiring see diagrams



## Attention

During commissioning apply a self adjustment drive.  
 Regard duty cycle at motor running times!  
 Never use spring return actuators without external load.

### Accessory InBox – adaptable terminal box



For electrical connection of ...Max actuators a terminal box is required.

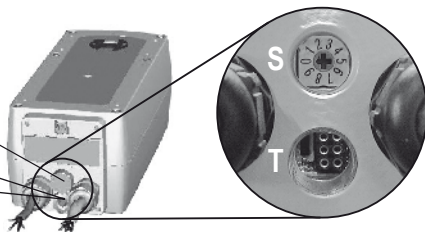
InBoxes are appropriate terminal boxes and placed at the disposal. To adapt the ...Box directly to the actuator housing a mounting bracket type MKK-S is required.

InBox- Y/S for ...Max-...-Y and ...-YF with integral auxiliary switches

## Parameters, adjustments and failure indication

Switch – Push button – Lamp  
for adjustment  
(behind the blanking plug)

- 10-position switch (S)  
Push button (T)  
3-colour LED



## Parameter selection

Example:  
InMax-15.30-Y

Requested parameter:  
Torque 30 N  
Motor running time 30 s/90°

Result:  
Switch position **07**

Type	Torques	
InMax- 5.10-Y ▶	5 N	10 N
<b>InMax- 15.30-Y ▶</b>	<b>15 N</b>	<b>30 N</b>
InMax- 5.10-YF ▶	5 N	10 N
InMax- 15-YF ▶	15 N	
	▼	▼
Running times	Position of switch S	
7,5 s/90° ▶	00	05
15 s/90° ▶	01	06
<b>30 s/90° ▶</b>	<b>02</b>	<b>07</b>
60 s/90° ▶	03	08
120 s/90° ▶	04	09

## Functions, adjustments and parameters

## A) Self adjustment of angle of rotation:

Switch (S) into position 02 (low torque) or 07 (high torque), then push button (T) for minimum 3 seconds. The actuator will drive into both end positions to be adjusted. LED indicates GREEN.

Adjustment time needs approx. 60 sec. (30 sec. "On", 30 sec. "Off"). After that, switch (S) into the position acc. with your required torque and running time.

## B) Selection of running time and torque:

Put switch (S) into the correct selected position in acc. to above table.

The selected parameter will work at next operation of the actuator.

Adjustment can be done even without supply voltage. If supply voltage is available turn switch only if actuator is not running.

## C) Running time spring return:

The running time of 3 or 10 sec. spring return is selected by wiring (see diagrams).

## D) Changing modulating mode into 3-pos. operation mode with feedback:

Push button (T) 3 times.

LED changes from permanent GREEN to permanent YELLOW.

Push button within following limits:

- Push for min. 0,2 sec. each
- Complete pushing (3 ×) within 5 sec.

LED – Status:

- GREEN (permanent) – Supply available, actuator is active in modulating mode
- YELLOW (permanent) – Supply available, actuator is active in 3-pos. (+ U) mode

## E) Changing 3-pos. mode with feedback into modulating operation mode:

Push button (T) 3 ×. LED changes from permanent YELLOW to permanent GREEN.

## F) Additional information for 3-pos. operation:

- a closed, b open = direction I
- b closed, a open = direction II
- a and b closed = motor doesn't work
- a and b opened = motor doesn't work

The rotation direction (I and II) depends on left/right mounting of the actuator to the damper/valve. You can change direction of the motor by changing electrical wiring of terminal 3 and 4.

## G) Reverse function:

Bridge between signal wise wiring 3–4 (cable B) gets a reverse function of input Y and feedback signals U.

## Important information for installation and operation

## A. Installation, commissioning, maintenance

All national and international standards, rules and regulations must be complied. For electrical connection a terminal box is requested (e.g. InBox-...).

**Attention:** If the actuator is put out of operation all rules and regulation must be applied. You have to cut the supply voltage before opening a terminal box!

The cable of the actuator must be installed in a fixed position and protected against mechanical and thermal damage. Connect potential earth. Avoid temperature transfer from armature to actuator! Close all openings with min. IP66. For outdoor installation a protective housing against sun, rain and snow should be applied to the actuator as well as a constant supply at terminal 1 and 2 for the integral heater. Actuators are maintenance free. An annual inspection is recommended. Actuators must not be opened by the customer.

## B. Manual override

Manual override only if supply voltage is cut. Use delivered socket wrench with slow motions, usage can be tight. **Attention:** Releasing or letting go the Allen key too fast at manual operating actuators with spring return causes risk of injury!

## C. Shaft connection, selection of running time

Actuators are equipped with a direct coupling double square shaft connection of 12 × 12 mm. For round shafts adaptors/clamping connection (accessories, e.g. KB-S) are available. The housing of the actuator is axially symmetrically built to select Open-close direction of the spring return function by left-right mounting. Using the 10-position switch different motor running times and spring return running times can be selected on site in acc. to the actuator type.

## D. 3-position control mode

...Max actuators are in the best way suitable for the 3-pos. operation. To protect such elements as gears and mounting elements against harmful influences like minimum pulse time, ...Max actuators are protected via internal electronics. It ignores impulses < 0.5 s, the cyclic duration must be min. 0.5 s. At changing direction the pause is 1 s.

## E. Spring return

Spring return function works only if the supply voltage for terminal 1 or 2 is cut. In the event of an electrical interruption, the spring returns to its end position even if supply voltage is available again during return function. Thereafter operation will continue.

## F. Operation at ambient temperatures below –20 °C

All actuators are equipped with a regulated integrated heating device designed for employments down to –40 °C ambient temperature. The heater will be supplied automatically by connecting the constant voltage supply on the clamps 1 and 2.

1. After mounting the actuator must be immediately electrically connected.
2. The heater switches on automatically when actuator reaches internally –20 °C. It heats up the actuator to a proper working temperature, then heater switches off automatically. Actuator will not run during heating process.
3. The adjustment options are only ensured after this heating up period.

## G. Excess temperatures

All actuators are protected against excess temperature. The internal thermostat works as a maximum limiter and, in the event of failure at incorrect temperatures, shuts off the actuator irreversible. An upstream connected temperature sensor stops the actuator before reaching its max. temperature. This safety feature is reversible, after cooling down the actuator is completely functional again. In this case the failure must be eliminated immediately on site!

## H. Synchron mode

Do not connect several actuators to one shaft or link mechanically together.

## I. Mechanical protection

The actuator must be operated with an outside load of at least 3 Nm.

After installing the actuator to the damper/armature an automatic alignment has to be accomplished in order to obtain a "gentle" blockade/stop. This function protects the damper/armature by reducing the end position's/blockade speed in order to avoid mechanical overload. The actuator aligns specifically once with 30 s/90° onto each position and recognizes the blockade position in order to reduce the motor performance during operation briefly before reaching the end/blockade position.

## ① Extra information (see additional data sheet)

Additional technical information, dimensions, installation instruction, illustration and failure indication